

# Absolute encoders – multiturn

<b>Compact electronic multiturn, optical</b>	<b>Sendix F3663 / F3683 (shaft / hollow shaft)</b>	<b>SSI / BiSS + incremental</b>
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The Sendix F36 multiturn with the patented Intelligent Scan Technology™ is an optical multiturn encoder in miniature format, without gears and with 100% insensitivity to magnetic fields.

With a size of just 36 x 42 mm it offers a through hollow shaft of up to 8 mm or a blind hollow shaft of up to 10 mm.



Safety-Lock™	High rotational speed	Temperature range -40°... +90°C	High protection level IP	High shaft load capacity	Shock / vibration resistant	Magnetic field proof	Reverse polarity protection	SinCos	Intelligent Scan Technology™	Surface protection salt spray-tested optional

## Reliable and insensitive

- Sturdy bearing construction in Safety-Lock™ design for resistance against vibration and installation errors.
- Reduced number of components ensures magnetic insensitivity.
- IP67 protection and wide temperature range -40 °C ... +90 °C.
- Patented Intelligent Scan Technology™ (with all singleturn and multiturn functions on one single OptoASIC) - offering highest reliability, a high resolution up to 41 bits and 100% magnetic field insensitivity.

## Optimized performance

- High precision with data refresh rate of the position value ≤ 1µs.
- High resolution feedback in real-time via incremental outputs SinCos and RS422.
- Short control cycles, clock frequency with SSI up to 2 MHz / with BiSS up to 10 MHz.

<b>Order code</b>	<b>8.F3663</b>	<b>.XXXX.XXX2</b>	If for each parameter of an encoder the <b>underlined preferred option</b> is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.	<b>10 by 10</b>							
<b>Shaft version</b>	Type	<table border="1"> <tr> <td style="text-align: center; font-size: x-small;">a</td> <td style="text-align: center; font-size: x-small;">b</td> <td style="text-align: center; font-size: x-small;">c</td> <td style="text-align: center; font-size: x-small;">d</td> <td style="text-align: center; font-size: x-small;">e</td> <td style="text-align: center; font-size: x-small;">f</td> <td style="text-align: center; font-size: x-small;">g</td> </tr> </table>	a	b	c	d	e	f	g		
a	b	c	d	e	f	g					
<b>a</b> Flange	1 = clamping flange, IP67, ø 36 mm [1.42"] 3 = clamping flange, IP65, ø 36 mm [1.42"] 2 = synchro flange, IP67, ø 36 mm [1.42"] <u>4 = synchro flange, IP65, ø 36 mm [1.42"]</u>	<b>c</b> Interface / supply voltage	1 = SSI, BiSS / 5 V DC <u>2 = SSI, BiSS / 10 ... 30 V DC</u> 3 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC 4 = SSI, BiSS + 2048 ppr. SinCos / 10 ... 30 V DC 5 = SSI, BiSS / 5 V DC, with sensor output 6 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC, with sensor output 7 = SSI, BiSS + 2048 ppr. RS422 / 5 V DC 8 = SSI, BiSS + 2048 ppr. RS422 / 10 ... 30 V DC	<b>e</b> Code	Optional on request B = SSI, binary - surface protection C = BiSS, binary - salt spray tested <u>G = SSI, gray</u> - other resolutions						
<b>b</b> Shaft (ø x L), with flat	1 = ø 6 x 12.5 mm [0.24 x 0.49"] <u>3 = ø 8 x 15 mm [0.32 x 0.59"]</u> 5 = ø 10 x 20 mm [0.39 x 0.79"] 2 = ø 1/4" x 12.5 mm [0.49"] 4 = ø 3/8" x 5/8"	<b>d</b> Type of connection	<u>1 = tangential cable, 1 m [3.28'] PUR</u> 3 = tangential cable, 5 m [16.40'] PUR U = tangential cable, 10 m [32.81'] PUR 5 = tangential cable, 1 m [3.28'] PUR with M12 connector for central fastening, 8-pin <sup>1)</sup>	<b>f</b> Resolution (singleturn)	B = 9 bit ST A = 10 bit ST 2 = 12 bit ST <u>3 = 13 bit ST</u> 4 = 14 bit ST 7 = 17 bit ST						
				<b>g</b> Resolution (multiturn)	<u>2 = 12 bit MT</u> 6 = 16 bit MT 4 = 24 bit MT						

1) Only with interface 1 and 2.

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<b>Order code</b>	<b>8.F3683</b>	<b>.XXXX.XXX2</b>		<p>If for each parameter of an encoder the <b>underlined preferred option</b> is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.</p>
<b>Hollow shaft</b>	Type	<b>a b c d e f g</b>	<b>10 by 10</b>	
<p><b>a Flange</b> 1 = with spring element, short, IP65 3 = with spring element, long, IP65 <u>2 = with stator coupling, IP65, ø 46 mm [1.81"]</u></p> <p><b>b Through hollow shaft</b> 1 = ø 6 mm [0.24"] 3 = ø 8 mm [0.32"] 2 = ø 1/4" <i>Blind hollow shaft</i> (insertion depth max. 14.5 mm [0.57"]) <u>4 = ø 10 mm [0.39"]</u></p>	<p><b>c Interface / supply voltage</b> 1 = SSI, BiSS / 5 V DC <u>2 = SSI, BiSS / 10 ... 30 V DC</u> 3 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC 4 = SSI, BiSS + 2048 ppr. SinCos / 10 ... 30 V DC 5 = SSI, BiSS / 5 V DC, with sensor output 6 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC, with sensor output 7 = SSI, BiSS + 2048 ppr. RS422 / 5 V DC 8 = SSI, BiSS + 2048 ppr. RS422 / 10 ... 30 V DC</p> <p><b>d Type of connection</b> <u>1 = tangential cable, 1 m [3.28'] PUR</u> 3 = tangential cable, 5 m [16.40'] PUR U = tangential cable, 10 m [32.81'] PUR 5 = tangential cable, 1 m [3.28'] PUR with M12 connector for central fastening, 8-pin <sup>1)</sup></p>	<p><b>e Code</b> B = SSI, binary C = BiSS, binary <u>G = SSI, gray</u></p> <p><b>f Resolution (singleturn)</b> B = 9 bit ST A = 10 bit ST 2 = 12 bit ST <u>3 = 13 bit ST</u> 4 = 14 bit ST 7 = 17 bit ST</p> <p><b>g Resolution (multiturn)</b> <u>2 = 12 bit MT</u> 6 = 16 bit MT 4 = 24 bit MT</p>	<p><i>Optional on request</i> - surface protection - salt spray tested - other resolutions</p>	

Mounting accessory for shaft encoders		Order no.
<b>Coupling</b>	Bellows coupling ø 19 mm [0.75"] for shaft 8 mm [0.32"]	<b>8.0000.1102.0808</b>
Mounting accessory for hollow shaft encoders		Order no.
Dimensions in mm [inch]		
<b>Torque pin, ø 4 mm</b>	with fixing thread	<b>8.0010.4700.0000</b>
for flange with spring element (flange type 3 + 6)		
Cables and connectors		Order no.
<b>Preassembled cables</b>	M12 female connector with coupling nut, 8-pin, A coded, straight open ended 2 m [6.56'] PUR cable	<b>05.00.6051.8211.002M</b>
<b>Connectors</b>	M12 female connector with coupling nut, 8-pin, A coded, straight (metal)	<b>05.CMB 8181-0</b>

Further Kübler accessories can be found at: [kuebler.com/accessories](http://kuebler.com/accessories)  
Further Kübler cables and connectors can be found at: [kuebler.com/connection-technology](http://kuebler.com/connection-technology)

1) Only with output circuits 1 and 2.

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## Technical data

### Mechanical characteristics

<b>Maximum speed</b>	
shaft version without shaft seal (IP65) or blind hollow shaft version	12000 min <sup>-1</sup> 10000 min <sup>-1</sup> (continuous)
shaft version with shaft seal (IP67) or hollow shaft version	10000 min <sup>-1</sup> 8000 min <sup>-1</sup> (continuous)
<b>Starting torque at 20 °C [68 °F]</b>	
without shaft seal	< 0.007 Nm
with shaft seal (IP67)	< 0.01 Nm
<b>Shaft load capacity</b>	radial 40 N axial 20 N
<b>Weight</b>	approx. 0.2 kg [7.06 oz]
<b>Protection</b>	housing side IP67 acc. to EN 60529 shaft side IP65 (solid shaft version opt. IP67)
<b>Working temperature range</b>	-40 °C ... +90 °C [-40 °F ... +194 °F]
<b>Materials</b>	shaft / hollow shaft stainless steel flange aluminum housing zinc die-cast cable PUR
<b>Shock resistance</b> acc. to EN 60068-2-27	2500 m/s <sup>2</sup> , 6 ms
<b>Vibration resistance</b> acc. to EN 60068-2-6	100 m/s <sup>2</sup> , 55 ... 2000 Hz

### Electrical characteristics

<b>Supply voltage</b>	5 V DC (±5 %) or 10 ... 30 V DC
<b>Current consumption</b> (no load)	5 V DC max. 60 mA 10 ... 30 V DC max. 30 mA
<b>Reverse polarity protection of the supply voltage</b>	yes (only with 10 ... 30 V DC)
<b>Short-circuit proof outputs</b>	yes <sup>1)</sup>

### SSI interface

<b>Output driver</b>	RS485 transceiver type
<b>Permissible load / channel</b>	max. +/- 30 mA
<b>Signal level</b>	HIGH typ 3.8 V LOW with I <sub>Load</sub> = 20 mA typ 1.3 V
<b>Resolution singleturn</b>	10 ... 17 bit
<b>Number of revolutions</b> (multiturn)	max. 24 bit
<b>Code</b>	binary or gray
<b>SSI clock rate</b>	50 kHz ... 2 MHz
<b>Data refresh rate</b>	ST resolution ≤ 14 bit ≤ 1 μs ST resolution ≥ 15 bit 4 μs
<b>Monoflop time</b>	≤ 15 μs

**Note:** If the clock cycle starts within the monoflop time a second data transfer begins with the same data. If the clock cycle starts after the monoflop time the cycle begins with the new values. The update rate is dependent on the clock speed, data length and monoflop time.

### BiSS interface

<b>Output driver</b>	RS485 transceiver type
<b>Permissible load / channel</b>	max. +/- 30 mA
<b>Signal level</b>	HIGH typ 3.8 V LOW with I <sub>Load</sub> = 20 mA typ 1.3 V
<b>Resolution singleturn</b>	10 ... 17 bit
<b>Number of revolutions</b> (multiturn)	max. 24 bit
<b>Code</b>	binary
<b>BiSS Clock rate</b>	50 kHz ... 10 MHz
<b>Max. update rate</b>	< 10 μs, depends on the clock rate and the data length
<b>Data refresh rate</b>	ST resolution ≤ 14 bit ≤ 1 μs ST resolution 17 bit 2.4 μs
<b>Note:</b>	- bidirectional, factory programmable parameters are: resolution, code, direction, alarms and warnings - CRC data verification

### Incremental outputs (A/B)

	SinCos	RS422 TTL-compatible
<b>Max. frequency -3dB</b>	400 kHz	400 kHz
<b>Signal level</b>	1 V <sub>pp</sub> (± 20%)	HIGH: min. 2.5 V LOW: max. 0.5 V
<b>Short circuit proof</b>	yes <sup>1)</sup>	yes <sup>1)</sup>
<b>Pulse rate</b>	2048 ppr	2048 ppr

### Status output

<b>Output driver</b>	open collector, internal pull up resistor 22 kOhm
<b>Permissible load</b>	max. 20 mA
<b>Signal level</b>	HIGH +V LOW < 1 V
<b>Active</b>	LOW

The status output serves to display various alarm or error messages. In normal operation the status output is HIGH (open collector with int. pull-up 22 kOhm).

An active status output (LOW) displays:  
LED fault (failure or ageing) – over-temperature – undervoltage  
In the SSI mode, the fault indication can only be reset by switching off the supply voltage to the device.

1) Short circuit proof to 0 V or to output when supply voltage correctly applied.

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SET input	
<b>Input</b>	active HIGH
<b>Input type</b>	comparator
<b>Signal level</b> (+V = supply voltage)	HIGH min. 60 % of +V, max: +V LOW max. 30 % of +V
<b>Input current</b>	< 0.5 mA
<b>Min. pulse duration (SET)</b>	10 ms
<b>Input delay</b>	1 ms
<b>New position data readable after</b>	1 ms
<b>Internal processing time</b>	200 ms
<p>The encoder can be set to zero at any position by means of a HIGH signal on the SET input. Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms, after which the new position data can be read via SSI or BiSS. Once the SET function has been triggered, the encoder requires an internal processing time of typ. 200 ms; during this time the supply voltage must not be switched off.</p> <p>The SET function should be carried out whilst the encoder is at rest.</p> <p>If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.</p>	

DIR input	
<p>Direction input: A HIGH signal switches the direction of rotation from the default cw to ccw. This inverted function can also be factory-programmed.</p> <p>If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.</p>	
<b>Response time (DIR input)</b>	1 ms

Power-ON
After Power-ON the device requires a time of approx. 150 ms before valid data can be read.
Hot plugging of the encoder should be avoided.

Approvals		
<b>UL compliant</b> in accordance with	File no. E224618	
<b>CE compliant</b> in accordance with	EMC Directive	2014/30/EU
	RoHS Directive	2011/65/EU

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## Terminal assignment

Interface	Type of connection	Features	Cable (isolate unused cores individually before initial start-up)													
1, 2	1, 3, U	SET, DIR, Status	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Stat	⊥			
			Core color:	WH	BN	GN	YE	GY	PK	BU	RD	VT	shield			
1, 2	5	SET, DIR	M12 connector, 8-pin													
			Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	⊥				
			Pin:	1	2	3	4	5	6	7	8	PH				
3, 4	1, 3, U	SET, DIR, 2048 SinCos	Cable (isolate unused cores individually before initial start-up)													
			Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	A	$\bar{A}$	B	$\bar{B}$	⊥
			Core color:	WH	BN	GN	YE	GY	PK	BU	RD	BK	VT	GY-PK	RD-BU	shield
5	1, 3, U	SET, DIR, Sensor output	Cable (isolate unused cores individually before initial start-up)													
			Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	0 V <sub>sens</sub>	+V <sub>sens</sub>	⊥		
			Core color:	WH	BN	GN	YE	GY	PK	BU	RD	VT	RD-BU	shield		
6	1, 3, U	2048 SinCos, Sensor output	Cable (isolate unused cores individually before initial start-up)													
			Signal:	0 V	+V	C+	C-	D+	D-	0 V <sub>sens</sub>	+V <sub>sens</sub>	A	$\bar{A}$	B	$\bar{B}$	⊥
			Core color:	WH	BN	GN	YE	GY	PK	BU	RD	BK	VT	GY-PK	RD-BU	shield
7, 8	1, 3, U	2048 incr. RS422	Cable (isolate unused cores individually before initial start-up)													
			Signal:	0 V	+V	C+	C-	D+	D-	A	$\bar{A}$	B	$\bar{B}$	⊥		
			Core color:	WH	BN	GN	YE	GY	PK	BK	VT	GY-PK	RD-BU	shield		

- +V: Supply voltage encoder +V DC
- 0 V: Supply voltage encoder ground GND (0 V)
- 0 V<sub>sens</sub> / +V<sub>sens</sub>: Using the sensor outputs of the encoder, the voltage present can be measured and if necessary increased accordingly.
- C+, C-: Clock signal
- D+, D-: Data signal
- A,  $\bar{A}$ : Incremental output channel A (cosine)
- B,  $\bar{B}$ : Incremental output channel B (sine)
- SET: Set input
- DIR: Direction input
- Stat: Status output
- PH ⊥: Plug connector housing (shield)

Top view of mating side, male contact base



M12 connector, 8-pin

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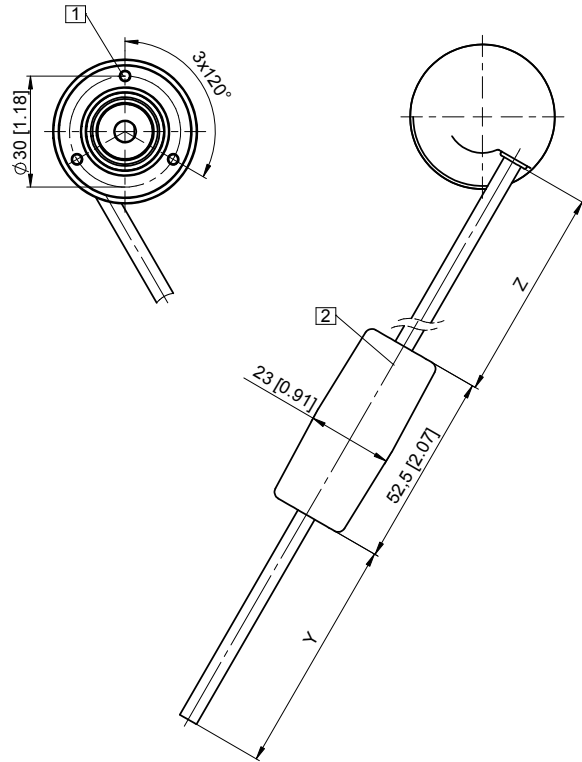
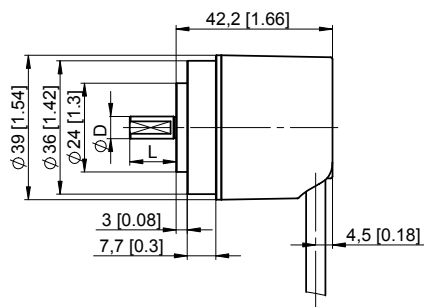
**SSI / BiSS**

## Dimensions shaft version

Dimensions in mm [inch]

**Clamping flange,  $\varnothing$  36 [1.42]**  
**Flange type 1 and 3**

- 1 3 x M3, 6 [0.24] deep
- 2 Battery (in the cable)



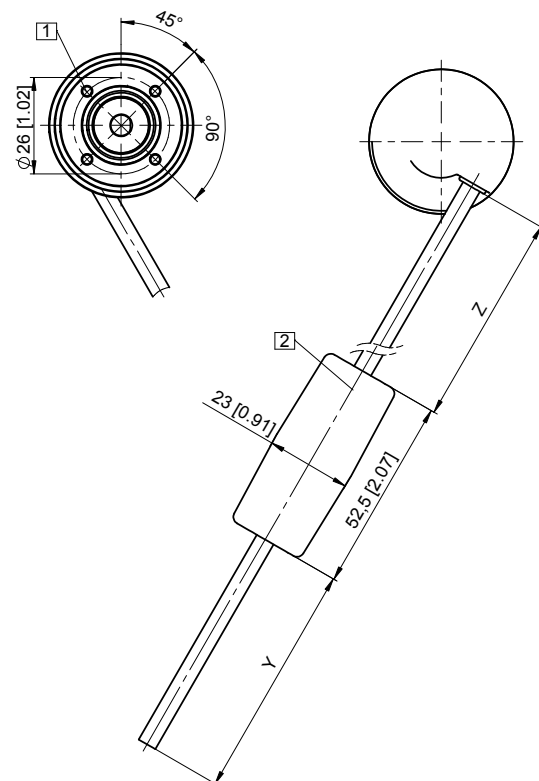
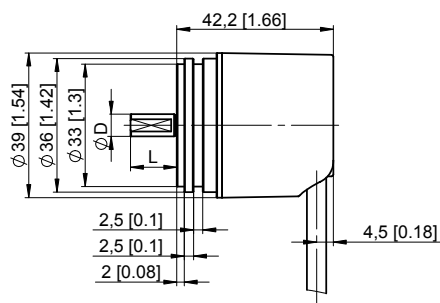
D	Fit	L
6 [0.24]	h7	12.5 [0.49]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
1/4"	h7	12.5 [0.49]
3/8"	h7	5/8"

Y	Z
1 m [3.28']	0.15 m [0.49']
5 m [16.40']	0.15 m [0.49']

## Synchro flange, $\varnothing$ 36 [1.42]

**Flange type 2 and 4**  
(drawing with cable)

- 1 4 x M3, 6 [0.24] deep
- 2 Battery (in the cable)



D	Fit	L
6 [0.24]	h7	12.5 [0.49]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
1/4"	h7	12.5 [0.49]
3/8"	h7	5/8"

Y	Z
1 m [3.28']	0.15 m [0.49']
5 m [16.40']	0.15 m [0.49']

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## Dimensions hollow shaft version

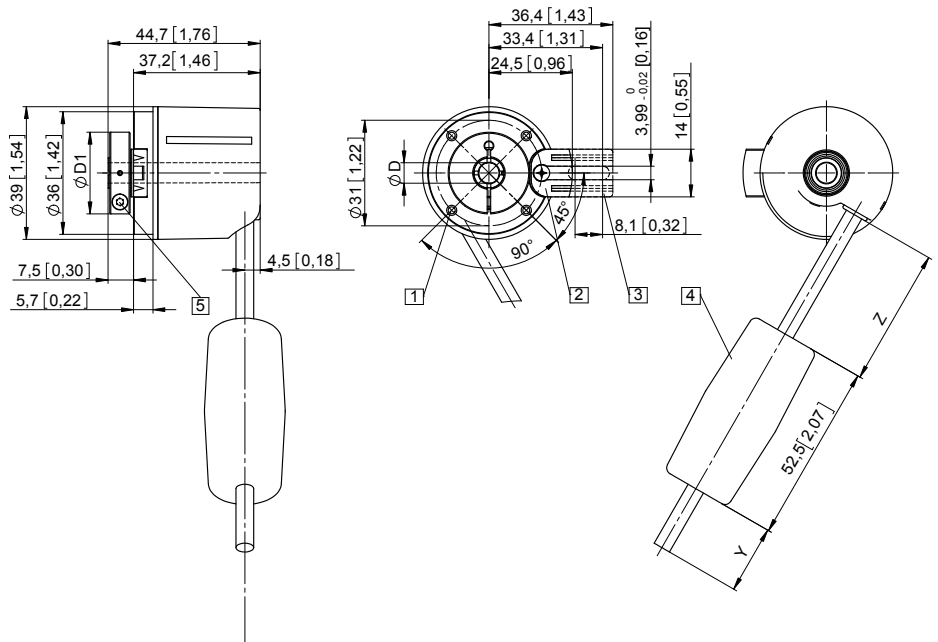
Dimensions in mm [inch]

### Flange with spring element

#### Flange type 1 and 3

(drawing with spring element short, spring element long is shown dashed)

- 1 4 x M2.5, 5 [0.20] deep
- 2 Spring element, short recommendation: torque pin DIN 7,  $\phi$  4 [0.16]
- 3 Spring element, long recommendation: torque pin DIN 7,  $\phi$  4 [0.16]
- 4 Battery (in the cable)
- 5 Recommended torque for the clamping ring 0.6 Nm



D	Fit	D1
6 [0.24]	H7	24 [0.94]
8 [0.32]	H7	25.5 [1.00]
10 [0.39] *)	H7	25.5 [1.00]
1/4"	H7	24 [0.94]

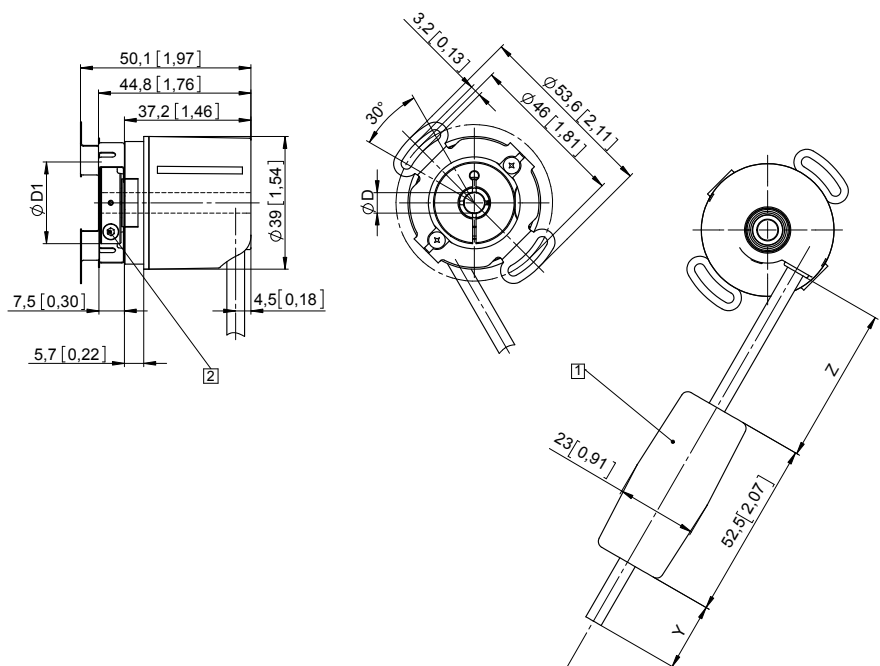
\*) Blind hollow shaft, insertion depth max. = 14.5 mm [0.57"]

Y	Z
1 m [3.28']	0.15 m [0.49']
5 m [16.40']	0.15 m [0.49']

### Flange with stator coupling, $\phi$ 46 [1.81]

#### Flange type 2

- 1 Battery (in the cable)
- 2 Recommended torque for the clamping ring 0.6 Nm



D	Fit	D1
6 [0.24]	H7	24 [0.94]
8 [0.32]	H7	25.5 [1.00]
10 [0.39] *)	H7	25.5 [1.00]
1/4"	H7	24 [0.94]

\*) Blind hollow shaft, insertion depth max. = 14.5 mm [0.57"]

Y	Z
1 m [3.28']	0.15 m [0.49']
5 m [16.40']	0.15 m [0.49']